GROUP ANALYSIS FOR KLEIN-GORDON EQUATION VIA THEIR SYMMETRIES Kapil Pal ${ }^{1}$, V. G. Gupta ${ }^{2}$ and Vatsala Pawar ${ }^{3}$<br>${ }^{1}$ Department of Mathematics, Jaipur National University, Jaipur, India-302017<br>${ }^{2}$ Department of Mathematics, University of Rajasthan, Jaipur, India-302004<br>${ }^{3}$ Department of Chemistry, Jaipur National University, Jaipur, India-302017<br>Email: kapilpal@jnujaipur.ac.in, guptavguor@rediffmail.com, vatsalapawar@jnujaipur.ac.in<br>Corresponding author: Kapil Pal, Email: palkapiljnu@gmail.com

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#### Abstract

In the present paper we have obtained the one parameter groups and symmetry transformations associated to the classical symmetries of the Klein-Gordon $(K G)$ equation, we have also constructed an optimal system of two dimensional sub-algebras of the $K G$ equation which provides the preliminary classification of group invariant solutions and yield the most general group invariant solution. 2020 Mathematical Sciences Classification: 17B66, 22E70, 35Q75, 46N50, 70G65, 81R05 Keywords and Phrases: Space Invariance, Translation, Rotation, Hyperbolic Rotation.


## 1 Introduction

Symmetry method for differential equations, was originally developed by Lie [8] these methods without any doubt are very useful and algorithmic for analyzing and solving linear and nonlinear differential equations. Classification of differential equation as well as linearization of them are some other important applications of symmetry transformation approach. Symmetry groups of a system of partial differential equation is a group of transformations $G$ on the space of independent and dependent variables which has the property that the elements of $G$ transform solution of the system to other solution of the system. The general prolongation formula for computing the symmetry groups for infinitesimal generators of a group of transformations was given by Olver $[11,12,13]$ for obtaining the group invariance solution of linear and non-linear differential equation. The group invariant solution of complex modified $K d V$ equation has been studied by Hyzel [3] and for the differential equation describing the radial jet having finite fluid velocity at orifice has been studied by Naeem \& Naz [9]. Pal et al. [14, 15] obtained the group invariant solution with the help of infinitesimal parameter. Hereman et al. [5], obtained the exact travelling wave solutions of $K G$ equation with cubic nonlinearity by using direct algebraic method. Ye and Zhang [16], obtained exact travelling wave solutions of $K G$ equation with cubic nonlinearity by using the bifurcation method and qualitative theory of dynamical systems. Dehghan and Ali [2], obtained numerical solutions of $K G$ equation with quadratic and cubic nonlinearity by using radial basis function and analyze the accuracy of their results with the analytical solutions. Jang [6], obtained the travelling wave solutions of nonlinear $K G$ equations. Gupta and Sharma [4] obtained the exact travelling wave solutions for the $K G$ equation with cubic nonlinearity by using First Integral Method. Other researcher also applied the different approaches to obtain the invariant solution of $K G$ equation $[7,10]$.

In this paper we extend the application of general prolongation formula to find the most general solution of the $K G$ equation

$$
\left(1 / c^{2}\right) u_{t t}=u_{x x}+u_{y y}-\left(m^{2} c^{2} / \hbar^{2}\right) u
$$

which use to model the two dimensional motion of free particle with mass $m$ (Bates[1]), where $u$ is wave function, $c$ denotes the velocity of light and $\hbar$ is plank constant.

## 2 Solution of Klein-Gordon Equation

We find the group invariant solution by calculating the symmetries for two-dimensional $K G$ equation for the motion of free particle with mass m . The equation

$$
\begin{equation*}
\left(1 / c^{2}\right) u_{t t}-u_{x x}-u_{y y}+\left(m^{2} c^{2} / \hbar^{2}\right) u=0 \tag{2.1}
\end{equation*}
$$

which is the second order differential equation with three independent variables and one dependent variable. A vector field on $\mathrm{X} \times \mathrm{U}$ takes the form

$$
\begin{equation*}
v=\xi(x, y, t, u) \partial_{x}+\eta(x, y, t, u) \partial_{y}+\tau(x, y, t, u) \partial_{t}+\phi(x, y, t, u) \partial_{u} \tag{2.2}
\end{equation*}
$$

where $\xi, \eta, \tau$ and $\phi$ are the smooth coefficient functions. Using General Prolongation formula (Olver[13], equation (2.38), page 110) the second prolongation of $v$

$$
\begin{align*}
p r^{(2)} v=v+\phi^{x}\left(\partial / \partial u_{x}\right)+\phi^{y}\left(\partial / \partial u_{y}\right) & +\phi^{t}\left(\partial / \partial u_{t}\right)+\phi^{x x}\left(\partial / \partial u_{x x}\right)+\phi^{x y}\left(\partial / \partial u_{x y}\right) \\
& +\phi^{x t}\left(\partial / \partial u_{x t}\right)+\phi^{y y}\left(\partial / \partial u_{y y}\right)+\phi^{y t}\left(\partial / \partial u_{y t}\right)+\phi^{t t}\left(\partial / \partial u_{t t}\right) \tag{2.3}
\end{align*}
$$

and the coefficients present in (2.3) are calculated by using (Olver[13], equation (2.39), page 110), and by the use of infinitesimal criterion of invariance (Olver[13], equation (2.26), page 104) the two-dimensional $K G$ equation takes the form

$$
\begin{equation*}
\left(\phi^{t t} / c^{2}\right)-\phi^{x x}-\phi^{y y}+\left(m^{2} c^{2} / \hbar^{2}\right) \phi=Q\left(\left(u_{t t} / c^{2}\right)-u_{x x}-u_{y y}+\left(m^{2} c^{2} / \hbar^{2}\right) u\right), \tag{2.4}
\end{equation*}
$$

in which $Q\left(x, y, t, u^{(2)}\right)$ depend up-to second order derivatives of $u$. By substituting the values of $\phi^{t t}, \phi^{x x}, \phi^{y y}$ and $\phi$ in equation (2.4) and equating the coefficients of the terms in the first and second order partial derivatives of $u$, the determining equations for the symmetry group of the two-dimensional $K G$ equation for a free particle are found as follows

## Table 2.1

| Monomial | Coefficient | Equation <br> Number | Monomial | Coefficient | Equation <br> Number |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | $\frac{\phi_{t t}}{c^{2}}-\phi_{x x}-\phi_{y y}+\frac{m^{2} c^{2} \phi}{\hbar^{2}}-\frac{m^{2} c^{2} Q u}{\hbar^{2}}=0$ | (40) | $u_{y t}$ | $-\frac{2 \eta_{t}}{c^{2}}+2 \tau_{y}=0$ | (20) |
| $u_{x}$ | $-\frac{\xi_{u t}}{c^{2}}-\left(2 \phi_{x u}-\xi_{x x}-\xi_{y y}\right)=0$ | (39) | $u_{x y}$ | $2 \eta_{x}+2 \xi_{y}=0$ | (19) |
| $u_{y}$ | $-\frac{\eta_{t t}}{c^{2}}-\left(2 \phi_{y u}-\eta_{x x}-\eta_{y y}\right)=0$ | (38) | $u_{t}$ | $\frac{\left(\phi_{u}-2 \tau_{t}\right)}{c^{2}}=\frac{Q}{c^{2}}$ | (18) |
|  | $\left(2 \phi_{t u}-\tau_{t t}\right)$ |  | $u_{x x}$ | $-\left(\phi_{u}-2 \xi_{x}\right)=-Q$ | (17) |
| $u_{t}$ | $\frac{c^{2}}{c^{2}}+\tau_{x x}+\tau_{y y}=0$ | (37) | $u_{y y}$ | $-\left(\phi_{u}-2 \eta_{y}\right)=-Q$ | (16) |
| $u_{x}^{2}$ | $-\left(\phi_{u u}-2 \xi_{x u}\right)=0$ | (36) |  | $\xi_{u}$ |  |
| $u_{y}^{2}$ | $-\left(\phi_{u u}-2 \eta_{\text {yu }}\right)=0$ | (35) | $u_{x} u_{t t}$ | $-\frac{\xi_{u}}{c^{2}}=0$ | (15) |
| $u_{t}^{2}$ | $\frac{\left(\phi_{u u}-2 \tau_{t u}\right)}{c^{2}}=0$ | (34) | $u_{y} u_{t t}$ | $-\frac{\eta_{u}}{c^{2}}=0$ | (14) |
| $u_{x}^{3}$ | $\xi_{\text {uu }}=0$ | (33) | $u_{t} u_{t}$ | $-\frac{3 \tau_{u}}{c^{2}}=0$ | (13) |
| $u_{y}^{3}$ | $\eta_{u u}=0$ | (32) |  |  |  |
| $u_{t}^{3}$ | $-\frac{\tau_{u u}}{c^{2}}=0$ | (31) | $u_{x} u_{x x}$ $u_{y} u_{x x}$ | $3 \xi_{u}=0$ $\eta_{u}=0$ | $(12)$ $(11)$ |
| $u_{x} u_{t}$ | $\frac{2 \xi_{t u}}{c^{2}}+2 \tau_{x u}=0$ | (30) | $u_{t} u_{x x}$ | $\tau_{u}=0$ | (10) |
|  |  |  | $u_{x} u_{y y}$ | $\xi_{u}=0$ | (9) |
| $u_{\nu} u_{t}$ | $\frac{2 \eta_{t u}}{2}+2 \tau_{v u}=0$ | (29) | $u_{y} u_{y y}$ | $3 \eta_{u}=0$ | (8) |
|  |  |  | $u_{t} u_{y y}$ | $\tau_{u}=0$ | (7) |
| $u_{x} u_{y}$ | $2 \xi_{y u}+2 \eta_{x u}=0$ | (28) |  | $\underline{2 \xi_{u}}{ }^{2}$ | (6) |
| $u_{x} u_{t}^{2}$ | $-\frac{\zeta_{u u}}{c^{2}}=0$ | (27) | $u_{t} u_{x t}$ |  | (6) |
| $u_{y} u_{t}^{2}$ | $-\frac{\eta_{u u}}{c^{2}}=0$ | (26) | $u_{t} u_{y t}$ | $-\frac{2 \eta_{u}}{c^{2}}=0$ | (5) |
| $u_{x}^{2} u_{t}$ | $\tau_{u u}=0$ | (25) | $u_{x} u_{x y}$ | $2 \eta_{u}=0$ | (4) |
| $u_{y}^{2} u_{t}$ | $\tau_{\text {uu }}=0$ | (24) | $u_{x} u_{x t}$ | $2 \tau_{u}=0$ | (3) |
| $u_{x}^{2} u_{y}$ | $\eta_{u u}=0$ | (23) | $u_{y} u_{x y}$ | $2 \xi_{u}=0$ | (2) |
| $u_{y}^{2} u_{x}$ | $\xi_{u u}=0$ | (22) | $u_{y} u_{y t}$ | $2 \eta_{u}=0$ | (1) |
| $u_{x t}$ | $-\frac{2 \xi_{t}}{c^{2}}+2 \tau_{x}=0$ | (21) |  |  |  |

The requirement for equations (1) to (15) is that $\xi, \eta$ and $\tau$ are independent of $u$, equations (16), (17) and (18) give $\xi_{x}=\tau_{t}=\eta_{y}$, equations (19), (20) and (21) give $\left(\xi_{t} / \mathrm{c}^{2}\right)=\tau_{x},\left(\eta_{t} / \mathrm{c}^{2}\right)=\tau_{y}$ and $\eta_{x}=-\xi_{y}$, equations (34), (35) and (36) give $\phi=\beta u+\alpha$ where $\alpha=\alpha(x, y, t)$ and $\beta=\beta(x, y, t)$ are functions. From the equation (37), (38) and (39) we get $\beta_{x}=0, \beta_{y}=0$ and $\beta_{t}=0$, from (40) we find $\beta=Q=c_{4}\left(\hbar^{2} / \mathrm{m}^{2} c^{2}\right)$. The most general infinitesimal symmetry of the two-dimensional $K G$ equation in ideal fluid has coefficient function of the form $\xi=c_{5} y+\left(c_{6} t+c_{2}\right) / c^{2}, \eta=-c_{5} x+\left(c_{7} t+c_{2}\right) / c^{2}, \tau=c_{6} x+c_{7} y+c_{1} c^{2}$ and $\phi=c_{4}\left(\hbar^{2} / m^{2} c^{2}\right) u+\alpha$ where $c_{1}, \ldots, c_{7}$ are arbitrary constant and $\alpha$ is an arbitrary solution of the $K G$ equation. The Lie algebras of infinitesimal symmetries of two-dimensional $K G$ equation for a free particle with mass $m$ is spanned by the seven vector fields $v_{1}=c^{2} \partial_{t}, v_{2}=c^{2} \partial_{x}, v_{3}=c^{2} \partial_{y}, v_{4}=\left(\hbar^{2} / m^{2} c^{2}\right) u \partial_{u}, v_{5}=y \partial_{x}-x \partial_{y}, v_{6}=c^{2}$ $t \partial_{x}+x \partial t, v_{7}=c^{2} t \partial_{x}+x \partial_{t}$, and the infinite-dimensional sub-algebra $v_{\alpha}=\alpha \partial_{u}$ where $\alpha$ is an arbitrary solution of two-dimensional $K G$ equation. The commutation relation between these vector fields are given by the following

## Table 2.2: Commutation-Relation

|  | $v_{1}$ | $v_{2}$ | $v_{3}$ | $v_{4}$ | $v_{5}$ | $v_{6}$ | $v_{7}$ | $v_{\alpha}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $v_{1}$ | 0 | 0 | 0 | 0 | 0 | $c^{2} v_{2}$ | $c^{2} v_{3}$ | $c^{2} v_{\alpha_{t}}$ |
| $v_{2}$ | 0 | 0 | 0 | 0 | $-v_{3}$ | $v_{1}$ | 0 | $c^{2} v_{\alpha_{x}}$ |
| $v_{3}$ | 0 | 0 | 0 | 0 | $v_{2}$ | 0 | $v_{1}$ | $c^{2} v_{\alpha_{y}}$ |
| $v_{4}$ | 0 | 0 | 0 | 0 | 0 | 0 | 0 | $-\left(\frac{\hbar^{2}}{m^{2} c^{2}}\right) v_{\alpha}$ |
| $v_{5}$ | 0 | $v_{3}$ | $-v_{2}$ | 0 | 0 | $v_{7}$ | $-v_{6}$ | $v_{\alpha_{1}}$ |
| $v_{6}$ | $-c^{2} v_{2}$ | $-v_{1}$ | 0 | 0 | $-v_{7}$ | 0 | $-c^{2} v_{5}$ | $v_{\alpha_{2}}$ |
| $v_{7}$ | $-c^{2} v_{3}$ | 0 | $-v_{1}$ | 0 | $v_{6}$ | $c^{2} v_{5}$ | 0 | $v_{\alpha_{3}}$ |
| $v_{\alpha}$ | $-c^{2} v_{\alpha_{t}}$ | $-c^{2} v_{\alpha_{x}}$ | $-c^{2} v_{\alpha_{y}}$ | $\left(\frac{\hbar^{2}}{m^{2} c^{2}}\right) v_{\alpha}$ | $-v_{\alpha_{1}}$ | $-v_{\alpha_{2}}$ | $-v_{\alpha_{3}}$ | 0 |

where $\alpha_{1}=y \alpha_{x}-x \alpha_{y}, \alpha_{2}=t c^{2} \alpha_{x}+x \alpha_{t}, \alpha_{3}=t c^{2} \alpha_{y}+y \alpha_{t}$.
The one-parameter groups $G_{i}$ generated by the $v_{i}$ are given as follows
$G_{1}:\left(x, y, t+c^{2} \varepsilon, u\right), G_{2}:\left(x+c^{2} \varepsilon, y, t, u\right), G_{3}:\left(x, y+c^{2} \varepsilon, t, u\right)$,
$\left.G_{4}:\left(x, y, t, e^{\left(\frac{\hbar^{2} \varepsilon}{m^{2} c^{2}}\right.}\right) u\right), G_{5}:(x \cos \varepsilon+y \sin \varepsilon, y \cos \varepsilon-x \sin \varepsilon, t, u)$,
$G_{6}:(x \cosh c \varepsilon+t c \sinh c \varepsilon, y, t \cosh c \varepsilon+(x / c) \sinh c \varepsilon, u)$,
$G_{7}:(x, y \cosh c \varepsilon+t c \sinh \varepsilon, t \cosh c \varepsilon+(y / c) \sinh c, \varepsilon)$,
$G_{\alpha}:(x, y, t, u+\varepsilon \alpha)$ where each $G_{i}$ is a symmetry group.
If we take $u=f(x, y, t)$ be a solution of the KG equation then the functions
$u^{(1)}=f\left(x, y, t-c^{2} \varepsilon\right), u^{(2)}=f\left(x-c^{2} \varepsilon, y, t\right), u^{(3)}=f\left(x, y-c^{2} \varepsilon, t\right)$,
$u^{(4)}=e^{\left(\frac{\hbar^{2} \varepsilon}{m^{2} c^{2}}\right)} f(x, y, t), u^{(5)}=f(x \cos \varepsilon-y \sin \varepsilon, y \cos \varepsilon+x \sin \varepsilon, t)$,
$u^{(6)}=f(x \cosh c \varepsilon-t c \sinh c \varepsilon, y, t \cosh c \varepsilon-(x / c) \sinh c \varepsilon)$,
$u^{(7)}=f(x, y \cosh c \varepsilon-t c \sinh c \varepsilon, t \cosh c \varepsilon-(y / c) \sinh \varepsilon)$,
$u^{(\alpha)}=f(x, y, t)+\varepsilon \alpha(x, y, t)$ where $\varepsilon$ is any real number and $\alpha(x, y, t)$ is any other solution to two dimensional $K G$ equation for a free particle with mass $m$. At the end the most general solution that we can obtain from a given solution $u=f(x, y, t)$, by group transformations is in the form given below

$$
\begin{align*}
& u=e^{\left(\frac{\hbar^{2} \varepsilon_{4}}{m^{2} c^{2}}\right)} f\left(x \cosh c \varepsilon_{6} \cdot \cos \varepsilon_{5}-t c \sinh c \varepsilon_{6}-y \sin \varepsilon_{5}-c^{2} \varepsilon_{2}\right. \\
& \\
& y \cosh c \varepsilon_{7} \cdot \cos \varepsilon_{5}-t c \sinh c \varepsilon_{7}+x \sin \varepsilon_{5}-c^{2} \varepsilon_{3}  \tag{2.5}\\
& \\
& \left.t \cosh c \varepsilon_{7} \cdot \cosh c \varepsilon_{6}-(y / c) \sinh c \varepsilon_{7}-(x / c) \sinh c \varepsilon_{6}-c^{2} \varepsilon_{1}\right)+\alpha(x, y, t)
\end{align*}
$$

where $\varepsilon_{1}, \ldots, \varepsilon_{7}$ are real constant and $\alpha$ be an arbitrary solution to two-dimensional $K G$ equation for free particle with mass $m$.

## 3 Special Case

If we take $\hbar=c=1$ then equation (2.5) reduces to

$$
\begin{aligned}
& u=e^{\left(\frac{\varepsilon_{4}}{m^{2}}\right)} f\left(x \cosh \varepsilon_{6} \cdot \cos \varepsilon_{5}-t \sinh \varepsilon_{6}-y \sin \varepsilon_{5}-\varepsilon_{2}\right. \\
& y \cosh \varepsilon_{7} \cdot \cos \varepsilon_{5}-t \sinh \varepsilon_{7}+x \sin \varepsilon_{5}-\varepsilon_{3} \\
& \left.t \cosh \varepsilon_{7} \cdot \cosh \varepsilon_{6}-y \sinh \varepsilon_{7}-x \sinh \varepsilon_{6}-\varepsilon_{1}\right) \\
& +\alpha(x, y, t)
\end{aligned}
$$

where $\varepsilon_{1}, \ldots \varepsilon_{7}$ are real constant and $\alpha$ be an arbitrary solution to two-dimensional $K G$ equation for free particle with $\hbar=c=1$ and mass $m$.

If we take $\mathrm{y}=0$ and $\hbar=c=1$ then equation (2.5) reduces to

$$
u=e^{\left(\frac{\varepsilon_{4}}{m^{2}}\right)} f\left(x \cosh \varepsilon_{6}-t \sinh \varepsilon_{6}-\varepsilon_{2}, t \cosh c \varepsilon_{6}-x \sinh \varepsilon_{6}-\varepsilon_{1}\right)+\alpha(x, t)
$$

where $\varepsilon_{1}, \ldots \varepsilon_{7}$ are real constant and $\alpha$ be an arbitrary solution to one-dimensional $K G$ equation for free particle with $\hbar=c=1$ and mass $m$.

## 4 Conclusion

In our investigation the symmetry group $G_{4}$ and $G_{\alpha}$ reflects the linearity of two-dimensional $K G$ equation for free particle with mass $m$. The group $G_{1}$ is space invariance symmetry group. The group $G_{2}$ and $G_{3}$ are time invariance group. The group $G_{5}$ represent rotational symmetry group. The group $G_{6}$ and $G_{7}$ are well-known hyperbolic rotational symmetry group.
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