

HYPERGEOMETRIC FORMS OF CERTAIN COMPOSITE FUNCTIONS INVOLVING ARCSINE(x) USING MACLAURIN SERIES AND THEIR APPLICATIONS

By

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Abstract

In this article, we obtain hypergeometric forms of some composite functions containing arcsine(x) like: $\exp(a \sin^{-1} x)$, $\frac{\exp(a \sin^{-1} x)}{\sqrt{1-x^2}}$, $\cos(b \sin^{-1} x)$, $\sin(b \sin^{-1} x)$, $\cosh(d \sin^{-1} x)$, $\sinh(d \sin^{-1} x)$, $\frac{\cos(b \sin^{-1} x)}{\sqrt{1-x^2}}$, $\frac{\sin(b \sin^{-1} x)}{\sqrt{1-x^2}}$ and arcsinh (x) like: $\exp(b \sinh^{-1} x)$, $\frac{\exp(b \sinh^{-1} x)}{\sqrt{1+x^2}}$, $\cos(g \sinh^{-1} x)$, $\sin(g \sinh^{-1} x)$, $\cosh(b \sinh^{-1} x)$, $\sinh(b \sinh^{-1} x)$, by using Leibniz theorem for successive differentiation, Maclaurin’s series expansion and Taylor’s series expansion, as the proof of the hypergeometric forms of the above functions is not available in the literature.

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1 Introduction and Preliminaries

In this paper, we shall use the following standard notations:

$\mathbb{N} := \{1, 2, 3, \dots\}$; $\mathbb{N}_0 := \mathbb{N} \cup \{0\}$; and $\mathbb{Z}_0^- := \mathbb{Z}^- \cup \{0\} = \{0, -1, -2, -3, \dots\}$.

The symbols $\mathbb{C}, \mathbb{R}, \mathbb{N}, \mathbb{Z}, \mathbb{R}^+$ and \mathbb{R}^- denote the sets of complex numbers, real numbers, natural numbers, integers, positive and negative real numbers respectively.

The Pochhammer symbol $(\alpha)_p$, $p \in \mathbb{C}$ is defined by ([10, p.22 Eq.(1), p.32, Q.N.(8) and Q.N.(9)],see also [12, p.23, Eq.(22) and Eq.(23)]).

A natural generalization of the Gaussian hypergeometric series ${}_2F_1[\alpha, \beta; \gamma; z]$ is accomplished by introducing any arbitrary number of numerator and denominator parameters[12, p.42, Eq.(1)].

Relation between hyperbolic and trigonometric functions:

(1.1) $\cos(i\theta) = \cosh(\theta)$, $\sin(i\theta) = i \sinh(\theta)$.

(1.2) $\sin^{-1}(x) = -i \sinh^{-1}(ix)$, $\sinh^{-1}(x) = -i \sin^{-1}(ix)$.

The Taylor’s series of a real or complex-valued function $y(x)$ which is infinitely differentiable at a real or complex number a , is the power series:

(1.3) $y(x) = (y)_{x=a} + (x - a)(y_1)_{x=a} + \frac{(x - a)^2}{2!}(y_2)_{x=a} + \frac{(x - a)^3}{3!}(y_3)_{x=a} + \frac{(x - a)^4}{4!}(y_4)_{x=a} + \dots$

(1.4) $= \sum_{n=0}^{\infty} \frac{(x-a)^n}{n!} (y_n)_{x=a}$

(1.5) $= \sum_{n=0}^{\infty} \frac{(x-a)^{2n}}{(2n)!} (y_{2n})_{x=a} + \sum_{n=0}^{\infty} \frac{(x-a)^{2n+1}}{(2n+1)!} (y_{2n+1})_{x=a}$.

The Maclaurin’s series is a particular case of Taylor’s series expansion of a function, about the origin i.e, when $a = 0$ in equation (1.3), the Maclaurin series is given as:

$y(x) = (y)_0 + x(y_1)_0 + \frac{x^2}{2!}(y_2)_0 + \frac{x^3}{3!}(y_3)_0 + \frac{x^4}{4!}(y_4)_0 + \frac{x^5}{5!}(y_5)_0 + \dots$

(1.6) $= \sum_{n=0}^{\infty} \frac{x^n}{n!} (y_n)_0$

(1.7) $= \sum_{n=0}^{\infty} \frac{x^{2n}}{(2n)!} (y_{2n})_0 + \sum_{n=0}^{\infty} \frac{x^{2n+1}}{(2n+1)!} (y_{2n+1})_0$,

where, $(y_m)_0 = \left(\frac{d^m y}{dx^m}\right)_{x=0}$.

The general Leibniz rule, named after Gottfried Wilhelm Leibniz, generalizes the product rule (which is also known as "Leibniz's rule"), which states that if $U(x)$ and $T(x)$ are n -times differentiable functions, then the product $U(x).T(x)$ is also n -times differentiable and its n th derivative is given by:

$$(1.8) \quad D^n[U(x) T(x)] = ({}^n C_0)(D^n U)(D^0 T) + ({}^n C_1)(D^{n-1} U)(D^1 T) + ({}^n C_2)(D^{n-2} U)(D^2 T) + \dots + ({}^n C_{n-1})(D^1 U)(D^{n-1} T) + ({}^n C_n)(D^0 U)(D^n T)$$

$$(1.9) \quad = \sum_{r=0}^n {}^n C_r (D^r T)(D^{n-r} U)$$

$$(1.10) \quad = \sum_{r=0}^n {}^n C_r (D^{n-r} T)(D^r U),$$

where $D = \frac{d}{dx}$.

Euler's linear transformation

$$(1.11) \quad {}_2F_1 \left[\begin{matrix} \beta, \lambda; \\ \mu; \end{matrix} z \right] = (1-z)^{\mu-\beta-\lambda} {}_2F_1 \left[\begin{matrix} \mu-\beta, \mu-\lambda; \\ \mu; \end{matrix} z \right],$$

where $\mu \in \mathbb{C} \setminus \mathbb{Z}_0^-$ and $|\arg(1-z)| < \pi$.

The present article is organized as follows. In section 3 we have given the proof of the hypergeometric forms of presented functions, because their proofs are not available in the literature[1, 2, 3, 4, 5, 6, 7, 8, 9] see also [11, 13]. So we are interested to give the proof of hypergeometric forms of some composite functions containing arcsine(x), using Maclaurin series. In section 4 we have obtained hypergeometric forms of some more functions by using the relations between inverse trigonometric and inverse hyperbolic functions. In section 5 we have discussed some applications of hypergeometric forms (2.1),(2.2) and (2.3). In section 6 we discussed some applications of hypergeometric forms (5.4) and (5.5).

2 Main Hypergeometric Forms of Certain Composite Functions

When the values of numerator, denominator parameters and arguments leading to the results which do not make sense are tacitly excluded, then each of the following hypergeometric form holds true:

$$(2.1) \quad \exp(a \sin^{-1} x) = {}_2F_1 \left[\begin{matrix} \frac{ia}{2}, -\frac{ia}{2}; \\ \frac{1}{2}; \end{matrix} x^2 \right] + ax {}_2F_1 \left[\begin{matrix} \frac{1+ia}{2}, \frac{1-ia}{2}; \\ \frac{3}{2}; \end{matrix} x^2 \right],$$

where $|x| < 1$.

$$(2.2) \quad \exp(b \sin^{-1} x) = \exp\left(\frac{\pi b}{2}\right) {}_2F_1 \left[\begin{matrix} ib, -ib; \\ \frac{1}{2}; \end{matrix} \frac{1-x}{2} \right],$$

where $|\frac{1-x}{2}| < 1$.

$$(2.3) \quad \frac{\exp(a \sin^{-1} x)}{\sqrt{1-x^2}} = {}_2F_1 \left[\begin{matrix} \frac{1+ia}{2}, \frac{1-ia}{2}; \\ \frac{1}{2}; \end{matrix} x^2 \right] + ax {}_2F_1 \left[\begin{matrix} \frac{2+ia}{2}, \frac{2-ia}{2}; \\ \frac{3}{2}; \end{matrix} x^2 \right],$$

where $|x| < 1$.

Note: In the above hypergeometric functions x, a and b can be purely real or purely imaginary or complex numbers.

3 Proof of Hypergeometric Forms

Proof of hypergeometric form (2.1)

Let

$$(3.1) \quad y = \exp(a \sin^{-1} x).$$

Put $x = 0$ in equation (3.1), we get

$$(3.2) \quad (y)_0 = 1.$$

Differentiate equation (3.1) w.r.t. x and put $x = 0$, we get

$$(3.3) \quad \sqrt{1-x^2} y_1 = ay,$$

$$(3.4) \quad (y_1)_0 = a.$$

Differentiate equation (3.3) w.r.t. x and put $x = 0$, we get

$$(3.5) (1 - x^2)y_2 - xy_1 - a^2y = 0,$$

$$(3.6) (y_2)_0 = a^2.$$

Differentiate equation (3.5) w.r.t. x and put $x = 0$, we get

$$(3.7) (1 - x^2)y_3 - 3xy_2 - (1 + a^2)y_1 = 0,$$

$$(3.8) (y_3)_0 = (1 + a^2)a.$$

Now differentiate equation (3.5) n -times w.r.t. x , and applying Leibnitz theorem we get

$$D^n \left\{ (1 - x^2)y_2 \right\} - D^n(xy_1) - D^n(a^2y) = 0 \quad ; n \geq 2,$$

$$(3.9) (1 - x^2)y_{n+2} - (2n + 1)xy_{n+1} - (n^2 + a^2)y_n = 0 \quad ; n \geq 2.$$

Put $x = 0$ in equation(3.9) we get

$$(3.10) (y_{n+2})_0 = (n^2 + a^2)(y_n)_0 \quad ; n \geq 2.$$

Put $n = 2, 3, 4, 5, 6, 7, 8, \dots$ in equations (3.10), we get

$$(3.11) (y_4)_0 = (2^2 + a^2)a^2,$$

$$(3.12) (y_5)_0 = (3^2 + a^2)(1 + a^2)a,$$

$$(3.13) (y_6)_0 = (4^2 + a^2)(2^2 + a^2)a^2,$$

$$(3.14) (y_7)_0 = (5^2 + a^2)(3^2 + a^2)(1 + a^2)a,$$

$$(3.15) (y_8)_0 = (6^2 + a^2)(4^2 + a^2)(2^2 + a^2)a^2,$$

$$(3.16) (y_9)_0 = (7^2 + a^2)(5^2 + a^2)(3^2 + a^2)(1 + a^2)a,$$

$$(3.17) (y_{10})_0 = (8^2 + a^2)(6^2 + a^2)(4^2 + a^2)(2^2 + a^2)a^2,$$

⋮

Recurrence Relation

In case of odd

$$(3.18) (y_{2n+1})_0 = a \prod_{j=1}^n \left\{ (2j - 1)^2 + a^2 \right\}.$$

In case of even

$$(3.19) (y_{2n})_0 = \prod_{j=1}^n \left\{ (2j - 2)^2 + a^2 \right\}.$$

We know by Maclaurin series expansion

$$(3.20) y = (y)_0 + x(y_1)_0 + \frac{x^2}{2!}(y_2)_0 + \frac{x^3}{3!}(y_3)_0 + \frac{x^4}{4!}(y_4)_0 + \frac{x^5}{5!}(y_5)_0 + \dots$$

Substitute the values of $(y)_0, (y_1)_0, (y_2)_0, (y_3)_0, (y_4)_0, (y_5)_0, \dots$ in equation (3.20), we get

$$y = \sum_{n=0}^{\infty} \frac{x^{2n}}{2n!} \prod_{j=1}^n \left\{ (2j - 2)^2 + a^2 \right\} + a \sum_{n=0}^{\infty} \frac{x^{2n+1}}{(2n+1)!} \prod_{j=1}^n \left\{ (2j - 1)^2 + a^2 \right\},$$

$$y = \sum_{n=0}^{\infty} \frac{x^{2n}}{2n!} \left\{ \prod_{j=1}^n [(2j - 2) + ia] \prod_{j=1}^n [(2j - 2) - ia] \right\} +$$

$$+ ax \sum_{n=0}^{\infty} \frac{x^{2n}}{(2n+1)!} \left\{ \prod_{j=1}^n [(2j - 1) + ia] \prod_{j=1}^n [(2j - 1) - ia] \right\},$$

$$y = \sum_{n=0}^{\infty} \frac{x^{2n} 2^{2n}}{2n!} \left\{ \prod_{j=1}^n \left[(j - 1) + \frac{ia}{2} \right] \prod_{j=1}^n \left[(j - 1) - \frac{ia}{2} \right] \right\} +$$

$$+ ax \sum_{n=0}^{\infty} \frac{x^{2n} 2^{2n}}{(2n+1)!} \left\{ \prod_{j=1}^n \left[(j - 1) + \frac{1}{2} + \frac{ia}{2} \right] \prod_{j=1}^n \left[(j - 1) + \frac{1}{2} - \frac{ia}{2} \right] \right\},$$

$$y = \sum_{n=0}^{\infty} \frac{x^{2n} \left(\frac{ia}{2}\right)_n \left(-\frac{ia}{2}\right)_n}{\left(\frac{1}{2}\right)_n n!} + ax \sum_{n=0}^{\infty} \frac{x^{2n} \left(\frac{1+ia}{2}\right)_n \left(\frac{1-ia}{2}\right)_n}{\left(\frac{3}{2}\right)_n n!}.$$

Using definition of generalized hypergeometric function of one variable, we get the required result (2.1).

Proof of hypergeometric forms (2.2) and (2.3)

The proof of hypergeometric form (2.2) can be given by following same approach and making use of Taylors series expansion. Similarly the proof of hypergeometric form (2.3) can be given by following same approach and making use of Maclaurin's series expansion. So we omit the details here.

4 Some Inverse Hyperbolic Sine Functions as Special Cases

Replacing x by ix in equation (2.1) and putting $a = -ib$, we get

$$(4.1) \quad \exp(b \sinh^{-1} x) = {}_2F_1 \left[\begin{matrix} -\frac{b}{2}, \frac{b}{2}; \\ \frac{1}{2}; \end{matrix} -x^2 \right] + bx {}_2F_1 \left[\begin{matrix} \frac{1+b}{2}, \frac{1-b}{2}; \\ \frac{3}{2}; \end{matrix} -x^2 \right].$$

Replacing x by ix in equation (2.2), and putting $b = -ia$, we get

$$(4.2) \quad \exp(a \sinh^{-1} x) = \exp\left(-\frac{i\pi a}{2}\right) {}_2F_1 \left[\begin{matrix} a, -a; \\ \frac{1}{2}; \end{matrix} \frac{1-ix}{2} \right].$$

Replacing x by ix in equation (2.3) and putting $a = -ib$, we get

$$(4.3) \quad \frac{\exp(b \sinh^{-1} x)}{\sqrt{(1+x^2)}} = {}_2F_1 \left[\begin{matrix} \frac{1+b}{2}, \frac{1-b}{2}; \\ \frac{1}{2}; \end{matrix} -x^2 \right] + bx {}_2F_1 \left[\begin{matrix} \frac{2+b}{2}, \frac{2-b}{2}; \\ \frac{3}{2}; \end{matrix} -x^2 \right].$$

5 Some Applications

5.1 Special Cases of Hypergeometric form (2.1)

Suppose $x \in \mathbb{R}$ and a is purely imaginary in equation (2.1), then put $a = ib$, where b is purely real, we get

$$(5.1) \quad \exp(ib \sin^{-1} x) = {}_2F_1 \left[\begin{matrix} -\frac{b}{2}, \frac{b}{2}; \\ \frac{1}{2}; \end{matrix} x^2 \right] + ibx {}_2F_1 \left[\begin{matrix} \frac{1+b}{2}, \frac{1-b}{2}; \\ \frac{3}{2}; \end{matrix} x^2 \right].$$

Applying Euler's formula on left hand side of equation (5.1), then on equating real and imaginary parts, we get

$$(5.2) \quad \cos(b \sin^{-1} x) = {}_2F_1 \left[\begin{matrix} -\frac{b}{2}, \frac{b}{2}; \\ \frac{1}{2}; \end{matrix} x^2 \right],$$

$$(5.3) \quad \sin(b \sin^{-1} x) = bx {}_2F_1 \left[\begin{matrix} \frac{1+b}{2}, \frac{1-b}{2}; \\ \frac{3}{2}; \end{matrix} x^2 \right].$$

Put $x = \sin(\theta)$ in equation (5.2) and (5.3), we get

$$(5.4) \quad \cos(b\theta) = {}_2F_1 \left[\begin{matrix} -\frac{b}{2}, \frac{b}{2}; \\ \frac{1}{2}; \end{matrix} \sin^2 \theta \right],$$

$$(5.5) \quad \sin(b\theta) = b \sin(\theta) {}_2F_1 \left[\begin{matrix} \frac{1+b}{2}, \frac{1-b}{2}; \\ \frac{3}{2}; \end{matrix} \sin^2 \theta \right].$$

Using Euler's linear transformation (1.11) in the right hand side of equations (5.4) and (5.5), we get

$$(5.6) \quad \cos(b\theta) = \cos \theta {}_2F_1 \left[\begin{matrix} \frac{1+b}{2}, \frac{1-b}{2}; \\ \frac{1}{2}; \end{matrix} \sin^2 \theta \right],$$

$$(5.7) \quad \sin(b\theta) = b(\sin \theta)(\cos \theta) {}_2F_1 \left[\begin{matrix} \frac{2-b}{2}, \frac{2+b}{2}; \\ \frac{3}{2}; \end{matrix} \sin^2 \theta \right].$$

Put $b = id$ in equation (5.2) and (5.3), where d is purely imaginary, we get

$$(5.8) \quad \cosh(d \sin^{-1} x) = {}_2F_1 \left[\begin{matrix} -\frac{id}{2}, \frac{id}{2}; \\ \frac{1}{2}; \end{matrix} x^2 \right],$$

$$(5.9) \quad \sinh(d \sin^{-1} x) = dx {}_2F_1 \left[\begin{matrix} \frac{1+id}{2}, \frac{1-id}{2}; \\ \frac{3}{2}; \\ x^2 \end{matrix} \right].$$

Putting $x = iy$ in equation (5.2) and (5.3), where y is purely imaginary, we get

$$(5.10) \quad \cosh(b \sinh^{-1} y) = {}_2F_1 \left[\begin{matrix} -\frac{b}{2}, \frac{b}{2}; \\ \frac{1}{2}; \\ -y^2 \end{matrix} \right],$$

$$(5.11) \quad \sinh(b \sinh^{-1} y) = by {}_2F_1 \left[\begin{matrix} \frac{1-b}{2}, \frac{1+b}{2}; \\ \frac{3}{2}; \\ -y^2 \end{matrix} \right].$$

Putting $x = iy$ and $b = ig$ in equation (5.2) and (5.3), where y and g are purely imaginary, we get

$$(5.12) \quad \cos(g \sinh^{-1} y) = {}_2F_1 \left[\begin{matrix} -\frac{ig}{2}, \frac{ig}{2}; \\ \frac{1}{2}; \\ -y^2 \end{matrix} \right],$$

$$(5.13) \quad \sin(g \sinh^{-1} y) = gy {}_2F_1 \left[\begin{matrix} \frac{1+ig}{2}, \frac{1-ig}{2}; \\ \frac{3}{2}; \\ -y^2 \end{matrix} \right].$$

5.2 Special Cases of Hypergeometric form (2.2)

Suppose $x \in \mathbb{R}$ and b is purely imaginary in equation (2.2), then put $b = ia$, where a is purely real, we get

$$(5.14) \quad \exp(ia \sin^{-1} x) = \exp\left(\frac{i\pi a}{2}\right) {}_2F_1 \left[\begin{matrix} -a, a; \\ \frac{1}{2}; \\ \frac{1-x}{2} \end{matrix} \right].$$

Applying Euler's formula on left hand side of equation (5.14), then on equating real and imaginary parts, we get

$$(5.15) \quad \cos(a \sin^{-1} x) = \cos\left(\frac{\pi a}{2}\right) {}_2F_1 \left[\begin{matrix} -a, a; \\ \frac{1}{2}; \\ \frac{1-x}{2} \end{matrix} \right],$$

$$(5.16) \quad \sin(a \sin^{-1} x) = \sin\left(\frac{\pi a}{2}\right) {}_2F_1 \left[\begin{matrix} -a, a; \\ \frac{1}{2}; \\ \frac{1-x}{2} \end{matrix} \right].$$

Put $a = id$ in equation (5.15) and (5.16), where d is purely imaginary, we get

$$(5.17) \quad \cosh(d \sin^{-1} x) = \cosh\left(\frac{\pi d}{2}\right) {}_2F_1 \left[\begin{matrix} -id, id; \\ \frac{1}{2}; \\ \frac{1-x}{2} \end{matrix} \right],$$

$$(5.18) \quad \sinh(d \sin^{-1} x) = \sinh\left(\frac{\pi d}{2}\right) {}_2F_1 \left[\begin{matrix} -id, id; \\ \frac{1}{2}; \\ \frac{1-x}{2} \end{matrix} \right].$$

Putting $x = iy$ in equation (5.15) and (5.16), where y is purely imaginary, we get

$$(5.19) \quad \cosh(a \sinh^{-1} y) = \cos\left(\frac{\pi a}{2}\right) {}_2F_1 \left[\begin{matrix} -a, a; \\ \frac{1}{2}; \\ \frac{1-iy}{2} \end{matrix} \right],$$

$$(5.20) \quad \sinh(a \sinh^{-1} y) = -i \sin\left(\frac{\pi a}{2}\right) {}_2F_1 \left[\begin{matrix} -a, a; \\ \frac{1}{2}; \\ \frac{1-iy}{2} \end{matrix} \right].$$

Putting $x = iy$ and $a = ig$, in equation (5.15) and (5.16), where y and g are purely imaginary, we get

$$(5.21) \quad \cos(g \sinh^{-1} y) = \cosh\left(\frac{\pi g}{2}\right) {}_2F_1 \left[\begin{matrix} -ig, ig; \\ \frac{1}{2}; \\ \frac{1-iy}{2} \end{matrix} \right],$$

$$(5.22) \quad \sin(g \sinh^{-1} y) = -i \sinh\left(\frac{\pi g}{2}\right) {}_2F_1 \left[\begin{matrix} -ig, ig; \\ \frac{1}{2}; \\ \frac{1-iy}{2} \end{matrix} \right].$$

5.3 Special Cases of Hypergeometric form(2.3)

Suppose $x \in \mathbb{R}$ and a is purely imaginary in equation (2.3), then put $a = ib$, where b is purely real, we get

$$(5.23) \quad \frac{\exp(ib \sin^{-1} x)}{\sqrt{(1-x^2)}} = {}_2F_1 \left[\begin{matrix} \frac{1-b}{2}, \frac{1+b}{2}; \\ \frac{1}{2}; \end{matrix} x^2 \right] + ibx {}_2F_1 \left[\begin{matrix} \frac{2-b}{2}, \frac{2+b}{2}; \\ \frac{3}{2}; \end{matrix} x^2 \right].$$

Applying Euler's formula on left hand side of equation (5.23), then on equating real and imaginary parts, we get

$$(5.24) \quad \frac{\cos(b \sin^{-1} x)}{\sqrt{(1-x^2)}} = {}_2F_1 \left[\begin{matrix} \frac{1-b}{2}, \frac{1+b}{2}; \\ \frac{1}{2}; \end{matrix} x^2 \right],$$

$$(5.25) \quad \frac{\sin(b \sin^{-1} x)}{\sqrt{(1-x^2)}} = bx {}_2F_1 \left[\begin{matrix} \frac{2-b}{2}, \frac{2+b}{2}; \\ \frac{3}{2}; \end{matrix} x^2 \right].$$

Put $b = id$, in equation (5.24) and (5.25), where d is purely imaginary, we get

$$(5.26) \quad \frac{\cosh(d \sin^{-1} x)}{\sqrt{(1-x^2)}} = {}_2F_1 \left[\begin{matrix} \frac{1-id}{2}, \frac{1+id}{2}; \\ \frac{1}{2}; \end{matrix} x^2 \right],$$

$$(5.27) \quad \frac{\sinh(d \sin^{-1} x)}{\sqrt{(1-x^2)}} = dx {}_2F_1 \left[\begin{matrix} \frac{2-id}{2}, \frac{2+id}{2}; \\ \frac{3}{2}; \end{matrix} x^2 \right].$$

Putting $x = iy$ in equation (5.24) and (5.25), where y is purely imaginary, we get

$$(5.28) \quad \frac{\cosh(b \sinh^{-1} y)}{\sqrt{(1+y^2)}} = {}_2F_1 \left[\begin{matrix} \frac{1-b}{2}, \frac{1+b}{2}; \\ \frac{1}{2}; \end{matrix} -y^2 \right],$$

$$(5.29) \quad \frac{\sinh(b \sinh^{-1} y)}{\sqrt{(1+y^2)}} = by {}_2F_1 \left[\begin{matrix} \frac{2-b}{2}, \frac{2+b}{2}; \\ \frac{3}{2}; \end{matrix} -y^2 \right].$$

Putting $x = iy$ and $b = ig$ in equation (5.24) and (5.25) where y and g are purely imaginary, we get

$$(5.30) \quad \frac{\cos(g \sinh^{-1} y)}{\sqrt{(1+y^2)}} = {}_2F_1 \left[\begin{matrix} \frac{1-ig}{2}, \frac{1+ig}{2}; \\ \frac{1}{2}; \end{matrix} -y^2 \right],$$

$$(5.31) \quad \frac{\sin(g \sinh^{-1} y)}{\sqrt{(1+y^2)}} = gy {}_2F_1 \left[\begin{matrix} \frac{2-ig}{2}, \frac{2+ig}{2}; \\ \frac{3}{2}; \end{matrix} -y^2 \right].$$

6 Some Applications of Hypergeometric Forms (5.4) and (5.5)

Replacing θ by $\left(\frac{\pi}{2} - \theta\right)$ in equations (5.4) and (5.5), we get

$$(6.1) \quad \cos(b\theta) = \cos\left(\frac{b\pi}{2}\right) {}_2F_1 \left[\begin{matrix} -\frac{b}{2}, \frac{b}{2}; \\ \frac{1}{2}; \end{matrix} \cos^2 \theta \right] + b \cos(\theta) \sin\left(\frac{b\pi}{2}\right) {}_2F_1 \left[\begin{matrix} \frac{1+b}{2}, \frac{1-b}{2}; \\ \frac{3}{2}; \end{matrix} \cos^2 \theta \right].$$

$$(6.2) \quad \sin(b\theta) = \sin\left(\frac{b\pi}{2}\right) {}_2F_1 \left[\begin{matrix} -\frac{b}{2}, \frac{b}{2}; \\ \frac{1}{2}; \end{matrix} \cos^2 \theta \right] - b \cos(\theta) \cos\left(\frac{b\pi}{2}\right) {}_2F_1 \left[\begin{matrix} \frac{1+b}{2}, \frac{1-b}{2}; \\ \frac{3}{2}; \end{matrix} \cos^2 \theta \right].$$

7 Conclusion

In this paper, we have obtained hypergeometric forms of some composite functions involving $\arcsin(x)$ and $\operatorname{arcsinh}(x)$, by using Maclaurin's series expansion and Taylor's series expansion. We conclude our present investigation by observing that hypergeometric forms of some other functions can be derived in an analogous manner. More over the results derived are significant. These are expected to find some potential applications in the fields of Mathematics and Engineering Sciences.

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