

GENERALIZED LAPLACE TRANSFORM OF BANACH SPACE VALUED DISTRIBUTIONS

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ABSTRACT

In this paper the generalized Laplace transform

$$F(s) = \frac{\Gamma(A)}{\Gamma(B)} \int_0^\infty (st) {}_1F_1(A, B; -st) f(t) dt$$

where $A = \beta + \eta + 1$; $B = \alpha + \beta + \eta + 1$ $\beta \geq 0$ and $\eta > 0$ has been extended to certain Banach-space-valued distributions (generalized functions).

An inversion formula for the above transform is also proved in distributional (Banach space valued) sense.

1. INTRODUCTION

The theory of distributions has been worked out in great depth by L. Schwartz [4]. Sebastiao Sliva [5] also has a theory for such vector-valued distributions. Zemanian [7,8], has presented the theory of Banach space valued distributions. He has also discussed the Laplace transform of Banach-space-valued distributions. Further he has used these concept for applications in system theory and signals.

Various generalizations of the Laplace transform defined by the equation

$$F(s) = \int_0^\infty e^{-st} f(t) dt \quad \dots (1.1)$$

have been studied by many mathematicians form time to time. One of such is given by

$$F(s) = \frac{\Gamma(A)}{\Gamma(B)} \int_0^\infty (st) {}_1F_1(A, B; -st) f(t) dt \quad \dots (1.2)$$

where $A = \beta + \eta + 1$; $B = \alpha + \beta + n + 1$; $\beta \geq 0$ and $\eta = 0$. (1.2) reduces to (1.1) for $\alpha = \beta = 0$. In an earlier paper [3] a complex inversion

formula for (1.2) has been extended to a class of generalized functions.

Motivated by the work of Zemanian [7, 8], we studied the transform defined by Eq. (1.2) for Banach-space-valued distributions. In this paper the complex inversion formula

$$\frac{f(t+) + f(t-)}{2} = \frac{1}{2\pi i} \int_{c-\infty}^{c+\infty} \frac{\Gamma(\alpha+n-s+1)t^{s-1}}{\Gamma(\beta+s)\Gamma(\eta-s+1)} \Phi(s) ds$$

where $\Phi(s) = \int_0^\infty x^{s-1} F(x) dx$, valid under certain conditions on $f(t)$ and parameters involved, has been extended to Banach-space-valued distributions for the transform (1.2).

The notation and terminology of this paper will follow that of Zemanian [7,8,9]. When U and V are two topological vector spaces, the symbol $[U; V]$ denotes the linear space of all continuous linear mappings of U into V . Note that throughout this work $D(A)$ will denote the space of smooth A -valued test functions with compact supports defined on $I = (0, \infty)$; A and B will denote Banach spaces, R the set of all real numbers, and C the set of all complex numbers.

2. The spaces $J_{c,d}(A)$ and $[J_{w,z}(A); B]$.

Given any two real numbers c and d , $J_{c,d}(A)$ is defined as the linear space of all A -valued smooth functions $\phi(t)$ from I into A such that $i_k(\phi(t)) = i_{c,d,k}(\phi(t))$.

$$= \sup_{t \in I} \left| \lambda_{c,d}(t) \left(t \frac{d}{dt} \right)^k t \phi(t) \right|_A < \infty, k = 0, 1, 2, \dots$$

where

$$\lambda_{c,d}(t) = \begin{cases} t^c, & 1 \leq t < \infty \\ t^d, & 0 < t < 1. \end{cases}$$

The locally convex topology of $J_{c,d}(A)$ is defined by the family of seminorms $\{i_k\}_{k=0}^\infty$. For $A = C$ we write $J_{c,d}(A) = J_{c,d}$. It is easy to see that $D(A) \subset J_{c,d}(A)$ and consequently $D \subset J_{c,d}$.

Now let $\{c_j\}_{j=1}^\infty$ be a strictly decreasing sequence in R tending to w where either $w \in R$ or $w = \infty$. Similarly let $\{d_j\}_{j=1}^\infty$ be a strictly increasing sequence in R tending to z , where either $z \in R$ or $z = \infty$.

The space defined by $J_{w,z}(A) = \bigcup_{j=1}^\infty J_{c_j,d_j}(A)$ is the inductive limit of the $J_{c_j,d_j}(A)$. It is a normal ρ -type testing function space.

Thus any continuous mapping f of $J_{w,z}(A)$ into B is called an $[A, B]$ -valued generalized function on I .

For a Banach space B , any $f \in [D(A); B]$ will be called a Banach-space-valued distribution. Upon setting $A = C$, f becomes a B -valued distribution and when $A = B = C$, f becomes a scalar distribution. The simple of weaker topology for $[D(A); B]$ is generated by the collection of seminorms $\{\gamma_\phi\}_\phi$, where ϕ traverse $D(A)$ and

$$\gamma_\phi(f) = \|\langle f, \phi \rangle\|_B.$$

We now come to the definition of $[J_{w,z}(A); B]$. If $\phi \in J_{w,z} : a \in A$, then $\phi a = a\phi$ is the function from I into A that assigns to each $t \in I$ the value $\phi(t) a$. Clearly $\phi a \in J_{w,z}(A)$. We denote by $J_{w,z} \Omega A$ the subspace of $J_{w,z}(A)$ consisting of elements of the form ϕa . If $g \in [J_{w,z}; C]$ and $a \in A$, $ga = ag$ is defined by

$$\langle ga, \phi \rangle = \langle g, \phi \rangle a, \phi \in J_{w,z} \quad \dots (2.1)$$

Clearly $ga \in [J_{w,z}; A]$. $[J_{w,z}; C] \Omega A$ denotes the subspace of $[J_{w,z}; A]$ consisting of all linear combinations of elements of the form ga . Similarly if $g \in [J_{w,z}; [A; B]]$ and $a \in A$, we define ga by equ. (2.1) again. Now $ga \in [J_{w,z}; B]$. $[J_{w,z}; [A; B]] \Omega A$ denotes the subspace of $[J_{w,z}; B]$ consisting of all linear combinations of elements of the form ga . Thus every $f \in [J_{w,z}(A); B]$ uniquely defines a $g \in [J_{w,z}; [A; B]]$ by means of the equation

$$\langle g, \phi \rangle a = \langle f, \phi a \rangle, \phi \in J_{w,z}, a \in A \quad \dots (2.2)$$

3. GENERALIZED LAPLACE TRANSFORM

Theorem 3.1. For every fixed $s, \beta \geq 0, \eta > 0$,

$$k(st) = \frac{\Gamma(A)}{\Gamma(B)} (st)^\beta {}_1F_1(A, B; -st) \in J_{c,d}$$

when $c < \eta$ and $d > -(1 + \beta)$

Proof : From Erdelyi [1], p. 254, we have

$$\frac{d}{dx} x^a {}_1F_1(a, c; x) = a x^{a-1} {}_1F_1(a+1, c; x) \quad \dots (3.1)$$

$$\|k(st)\|_{c,d} = \sup_{t \in I} \|\lambda_{c,d}(t) (t \frac{d}{dt})^h k(st)\|_A$$

$$= \sup_{t \in I} \|\lambda_{c,d}(t) (t \frac{d}{dt})^h t \frac{\Gamma(A)}{\Gamma(B)} (st)^\beta {}_1F_1(A, B; -st)\|_A$$

$$= \sup_{t \in I} \|\lambda_{c,d}(t) \frac{\Gamma(A+k)}{\Gamma(B)} t(st)^\beta {}_1F_1(A+k, B; -st)\|_A$$

by (3.1)

From Slater [6], p.59, it follows that

$${}_1F_1(a, b-x) = o(1), x \rightarrow 0$$

and ${}_1F_1(a, b; -x) = \frac{\Gamma(b)}{\Gamma(b-a)} x^{-a} \{1 + o(|x|^{-1})\}, x \rightarrow \infty, \operatorname{Re} b > \operatorname{Re} a > 0.$

When $0 < t < 1,$

$$i_{c,d,k}[k(st)] = \sup_{t \in I} \left\| \frac{\Gamma(A+K)}{\Gamma(B)} t^{d+1} (st) {}_1F_1(A+k, B; -st) \right\|_A, w$$

which is bounded as $x \rightarrow 0$ when $d > -(1 + \beta).$

Again, for $|t| \rightarrow \infty,$

$$i_{c,d,k}[k(st)] = \sup_{t \in I} = \left\| \frac{\Gamma(a+k)}{\Gamma(B)} t^{c+1} (st)^\beta {}_1F_1(A+k, B; -st) \right\|_A,$$

which is bounded when $c < \eta.$ This completes our proof.

Now let $f \in [J_{w,z}; B],$ and we define the generalized Laplace transform $F(s)$ of f by

$$F(s) = \langle f(t), k(st) \rangle. \quad \dots (3.2)$$

The left-hand side of $F(s)$ is a B -valued function. It can be shown as in [2] that $F(s)$ defined by (3.2) in an analytic function and

$$\frac{d}{ds} F(s) = \langle f(t), \frac{d}{ds} k(st) \rangle.$$

Similarly if $y \in [J_{w,z}(A); B],$ the generalized Laplace transform $Y(s)$ of y is defined as the generalized Laplace transform of $f_y,$

$$Y(s) = \langle f_y(t), k(st) \rangle \quad \dots (3.3)$$

where $f_y \in [J_{w,z}; [A; B]].$ The above definition is meaningful because corresponding to y we have a unique f_y as discussed in the previous section. Note that $Y(s)$ is an $[A; B]$ -valued function.

4. AN INVERSION THEOREM

We need the following three lemmas for the proof of inversion theorem.

Lemma 4.1 : Let $y \in [J_{w,z}(A); B], f_y$ be the corresponding member in $[J_{w,z} [A; B]]$ and

$$k(sx) = \frac{\Gamma(A)}{\Gamma(B)} (sx)^\beta {}_1F_1(A, B; -sx).$$

Then $\int_0^\infty x^{s-1} \langle f(u), k(xu) \rangle dx = f(u), \int_0^\infty x^{s-1} h(xu) dx >$

Lemma 4.2 : Let $y \in [J_{w,z}(A); B], \phi \in D(A)$ and

$$P(s) = \int_0^\infty t^{s-1} \phi(t) dt.$$

Then, for any two fixed real numbers r and c such that $0 < r < \infty, s = \sigma + iT$ with c fixed and $c < \operatorname{Re} s - 1 < d, -\infty < T < \infty,$

$$\begin{aligned} \frac{1}{2\pi} \int_{-r}^r \langle f_y(u), u^{-s} \rangle \Gamma(s) dT \\ = \langle y(u), \frac{1}{2\pi} u^{-\varepsilon} P(s) dT \rangle \end{aligned}$$

Lemma 4.3. If $\phi \in D(A)$, then

$$\frac{1}{\pi} \int_0^\infty \phi(x) \left(\frac{x}{u}\right)^{\sigma-1} [\sin r \log(x/u)] [u \log(x/u)]^{-1} dx$$

tends to $\phi(u)$ in $J_{w,z}(A)$ as $r \rightarrow \infty$

Except for some obvious changes, the proofs of these above lemmas are respectively the same as those of Lemmas 2.1, 2.2 and 2.3 in [3].

Theorem 4.1. If $y \in [J_{w,z}(A); (A); B]$, and let $Y(x)$ be the generalized Laplace transform of Banach space-valued distribution y , then in the sense of weak convergence in $[D(A); B]$, for $c+1 < \operatorname{Re} s < d+1$

$$\begin{aligned} \lim_{r \rightarrow \infty} \langle \frac{1}{2\pi i} \int_{\sigma-ir}^{\sigma+ir} \frac{\Gamma(\alpha + \eta - s + 1)}{\Gamma(\beta + s) \Gamma(\eta - s + 1)} M(s) t^{s-1} ds, \phi(t) \rangle \\ = \langle y, \phi \rangle \end{aligned}$$

where $M(s) = \int_0^\infty x^{s-1} y(x) dx.$

Proof. On substituting

$$\frac{\Gamma(\alpha + \eta - s + 1)}{(\beta + S) \Gamma(\eta - s + 1)} = Q$$

$$= \langle \frac{1}{2\pi} \int_{-r}^r Q M(s) t^{s-1} ds, \phi(\tau) \rangle. \quad \dots (4.1)$$

Since the integral on s is an A -valued continuous function on t , it is a regular A -valued distribution and therefore the left-hand side can be written as

$$\frac{1}{2\pi} \int_0^\infty \phi(t) \int_{-r}^r Q M(s) t^{s-1} dT dt, r > 0.$$

Since $y(x)\phi(t)$ is of bounded support and the integrand $Y(x)\phi(t)$ is a continuous B -valued function of (t, T) , the order of integration may be changed to obtain

$$\frac{1}{2\pi} \int_{-r}^r Q M(s) \int_0^\infty \phi(t) t^{s-1} dt dT$$

That is,

$$\frac{1}{2\pi} \int_{-r}^r Q \left(\int_0^\infty x^{s-1} \langle y(u), k(xu) \rangle dx \right) \int_0^\infty t^{s-1} \phi(t) dt dT$$

which by Lemma 4.1 is the same as

$$\frac{1}{2\pi} \int_{-r}^r Q \langle y(u), \int_0^\infty x^{s-1} k(xu) dx \rangle \int_0^\infty t^{s-1} \phi(t) dt dT. \quad \dots (4.2)$$

Since from Erdelyi [1, p. 285], we have

$$\int_0^\infty \frac{\Gamma(\alpha + \eta - s + 1)}{\Gamma(\beta + s) \Gamma(\eta - s + 1)} x^{s-1} k(xu) dx = u^{-s},$$

(4.2) can be rewritten as

$$\frac{1}{2\pi} \int_{-r}^r \langle y(u), u^{-s} \rangle \int_0^\infty t^{s-1} \phi(t) dt dT.$$

Again since ϕ is of bounded support and the integrand is a continuous B -valued function of (t, T) , the order of integration for the above repeated integral may be changed to obtain

$$\langle y(u), \frac{1}{2\pi} \int_0^\infty \phi(t) \int_{-r}^{r-s} u^{-s} t^{s-1} dT dt \rangle. \quad \dots (4.3)$$

Since $\int_{-r}^{r-s} u t^{s-1} dT = 2(t/u)^{\sigma-1} [u \log(t/u)]^{-1} \sin [r \log(t/u)]$,

(4.3) is the same as

$$\langle y(u), \frac{1}{\pi} \int_0^\infty \phi(t) (t/u)^{\sigma-1} [u \log(t/u)]^{-1} \sin [r \log(t/u)] dx \rangle. \quad \dots (4.4)$$

Now since $y \in [J_{w,z}(A); B]$ and by Lemma 4.3, the Banach-space-valued testing function in (4.4) converges to $\phi(U)$ in

$J_{w,z}(A)$, (4.4) tends to $\langle y, \phi \rangle$ as $r \rightarrow \infty$, and that completes the proof.

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