

ON AN EXTENSION OF A FIXED POINT THEOREM OF MEIR AND KEELER FOR THREE MAPPINGS

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Following Park and Bae [3], in this note we generalize the result of Meir and Keeler [2] to three mappings under Ćirić type [1] condition.

1. Singh and Singh [6] have given the following mapping condition for three mappings:

$$(1) \quad d(fx, gy) \leq \alpha \max \{ d(hx, hy), d(fx, hx), d(gy, hy), \\ \frac{1}{2} [d(fx, hy) + d(gy, hx)] \}, \text{ where}$$

$\alpha \in (0, 1)$, f, g, h are mappings from X into itself, h is continuous and $fh = hf, gh = hg$ and $f(X) \cup g(X) \subseteq h(X)$.

Borrowing the idea of three maps from the above, we define the Meir-Keeler type mapping condition for three maps as follows:

The self-maps f and g of X are called an (ϵ, δ) - h contraction if for $\epsilon > 0$, there exists $\delta = \delta(\epsilon) > 0$ such that for all $x, y \in X$,

$$(2) \quad \epsilon \leq \max \{ d(hx, hy), d(fx, hx), d(gy, hy), [d(fx, hy) \}$$

$\{ d(fx, gy) + d(gy, hx) \} / 2 \} < \varepsilon + \delta(\varepsilon)$ implies

$$d(fx, gy) < \varepsilon.$$

We take h continuous, $fh = hf$, $gh = hg$, and $f(X) \cup g(X) \subseteq h(X)$.

Let C_h denote the class of self maps f and g satisfying above.

Given a point x_0 in X , we consider a sequence $\{hx_n\}_{n=1}^{\infty}$ recursively,

given by the rule $hx_{2n+1} = fx_{2n}$, $hx_{2n+2} = gx_{2n+1}$, $n = 0, 1, 2, \dots$;

with the understanding that, if $hx_{2n+1} = hx_{2n+2}$ for some n , then

$hx_{2n+1} = hx_{2(n+j)}$ for each $j \geq 0$. Such a sequence $\{hx_n\}_{n=1}^{\infty}$ is called

an h -iteration of x_0 under f and g respectively. For an (ε, δ) - h contraction f, g we have from (2):

$$(3) \quad d(fx, gy) < \max \{ d(hx, hy), d(fx, hx), d(gy, hy),$$

$$[d(fx, hy) + d(gy, hx)] / 2 \}, \text{ for}$$

three pairs (x, y) for which the right hand side of (3) is positive.

2. We require the following two lemmas:

Lemma 1. *Let h be a self-map of metric space X and f, g be (ε, δ) - h contraction. If there exists an $x_0 \in X$ and h -iteration $\{hx_n\}_{n=1}^{\infty}$ of x_0 under f and g , then*

$$\inf. \{ d(hx_n, hx_{n+1}) \mid n = 1, 2, \dots \} = 0.$$

The proof runs parallel to that for lemma 2.1 in [3].

Lemma 2. *Let f, g be (ε, δ) -contraction commuting with h . If there exists a $z \in X$ such that $hz = fz = gz$, then hz is the unique common fixed point of f, g and h .*

Proof. Let $fz = hz = gz = v$. Suppose that $hv \neq v$.

Then $d(v, hv) = d(fz, hgz) = d(fz, ghz) < \max,$

$\{ d(hz, h^2z), d(hz, fz), d(h^2z, ghz), [d(fz, h^2z) + d(ghz, hz)]/2 \},$

where $h^2z = h(hz)$. Therefore, $d(v, hv) < d(v, hv)$, a contradiction.

Hence $hv = v$ and $fv = fhz = hfv = hv = v$ and also $gv = v$. Therefore, hz is a common fixed point of f, g and h . Uniqueness easily follows.

3. Now we state our main result:

Theorem 1. *Let h be a self-map of a metric space X and f, g be (ε, δ) - h contraction commuting with h . If a point $x_0 \in X$ has any h -iteration of x_0 under f and g with a cluster point $z \in X$ at which f, g, h are continuous, then $\{hx_n\}$ converges to z and hz is the common fixed point of f and g .*

Proof. By Lemma 2, it is sufficient to find a point $z \in X$ such that $fz = hz = gz$.

Let $x_0 \in X$ and let $\{hx_n\}_{n=1}^{\infty}$ be an h -iteration of x_0 under f and g . By Lemma 1, $\inf_n d(hx_{2n+1}, hx_{2n+2}) = 0$. If there exists an n such that $d(hx_{2n+1}, hx_{2n+2}) = 0$, then $hx_{2n+1} = fx_{2n} = gx_{2n+1}$, and we are finished. Let us assume that $d(hx_{2n+1}, hx_{2n+2}) \neq 0$ for every n . Following the proofs of Theorem 2.3 [3] and Theorem 4 [4], we can easily show that $\{hx_n\}$ is Cauchy, hence convergent to a point $z \in X$. Since $hhx_{2n} = hf x_{2n-1} = fhx_{2n-1}$ the continuity of h and f at z implies $hz = fz$. Similarly, $hz = gz$, as g is also continuous at z . This completes the proof.

If $f(x) \cup g(x) \subseteq h(x)$, then every $x_0 \in X$ has an h -iteration under f, g . Therefore, from Theorem 1 we have:

Theorem 2. *Let h be a continuous self-map of a complete metric*

space (X, d) , f, g be (ε, δ) - h contraction in C_h and continuous. Then f, g and h have a common fixed point w in X , and, for any $x_0 \in X$, any h -iteration of x_0 under f and g converges to some $z \in X$ satisfying $hz = w$.

Proof. It follows easily from Theorem 1 above.

Remark. 1. For $f = g$ in our Theorem 2, we have the Theorem 4 of Park and Rhoades [4] which, in turn, is an extension of the work of Ćirić [1] for a single mapping. In fact, Theorem 4 [4] is an extension of the earlier basic result of Park and Bae [3] for Meir and Keeler type [2] mapping. It will not be discourteous to mention that the author of the present paper obtained Theorem 4 of Park and Rhoades [4] independently, based upon the mapping condition of Ćirić [1] and the technique of Park and Bae [3] in mid. 1981, and thereby generalized it for three maps, as presented in the present note.

Remark 2. Note that $(1) \Rightarrow (2) \Rightarrow (3)$. For two mappings, i. e., for $f = g$, Rhoades [5] has shown that $(1) \Rightarrow (3)$, and not conversely. In view of the fact that $(3) \not\Rightarrow (1)$, our Theorems 1 and 2 are extensions of the result of Singh and Singh [6].

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